

## Customizable Computing at Datacenter Scale

Jason Cong

Chancellor's Professor, UCLA

Director, Center for Domain-Specific Computing

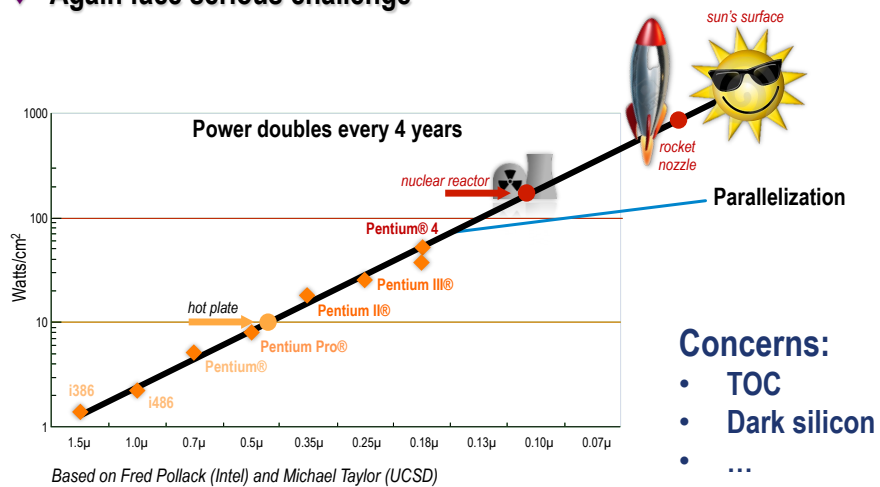
[cong@cs.ucla.edu](mailto:cong@cs.ucla.edu)

<http://cadlab.cs.ucla.edu/~cong>

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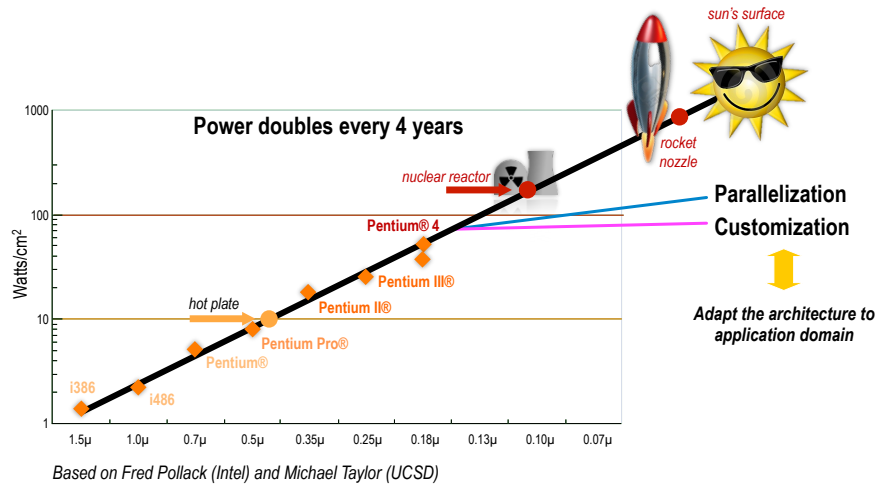
## Challenge with Processor Design – Power Barrier

- ◆ Current solution: *Parallelization*
- ◆ Again face serious challenge



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## CDSC Focus: Customization and Specialization



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## NSF awards UCLA \$10 million to create customized computing technology

By Wileen Wong Kromhout | 8/11/2009 9:45:00 AM

The UCLA Henry Samueli School of Engineering and Applied Science has been awarded a \$10 million grant by the National Science Foundation's Expeditions in Computing program to develop high-performance, energy efficient, customizable computing that could revolutionize the way computers are used in health care and other important applications.

In particular, UCLA Engineering researchers will demonstrate how the new technology, known as domain-specific computing, could transform the role of medical imaging and hemodynamic simulation, providing more cost-effective and convenient solutions for preventive, diagnostic and therapeutic procedures and dramatically improving health care quality, efficiency and patient outcomes.

"This significant award is another testament to the world-class faculty here at UCLA who continue to push the envelope to solve society's most pressing issues," said UCLA Chancellor Gene Block. "We are grateful to the NSF, which has repeatedly provided crucial funding to our faculty, helping to place the university among the nation's top five in research funding."

In an effort to meet ever-increasing computing needs in various fields, the computing industry has entered an "era of parallelization," in which tens of thousands of computer servers are connected in warehouse-scale data centers, said Jason Cong, the Chancellor's Professor of Computer Science and director of the new UCLA Center for Domain-Specific Computing (CDSC), which will oversee the research. But these parallel, general-purpose computing systems still face serious challenges in terms of performance, energy, space and cost.

Domain-specific computing holds significant advantages, Cong said. While general-purpose computing relies on computer architecture and languages aimed at any type of application, domain-specific computing utilizes a customizable architecture and custom-oriented, high-level computer languages tailored to a particular application area or domain — in this case, medical imaging and hemodynamic modeling. This customization ultimately results in much less energy consumption, faster results, lower costs and increased productivity.

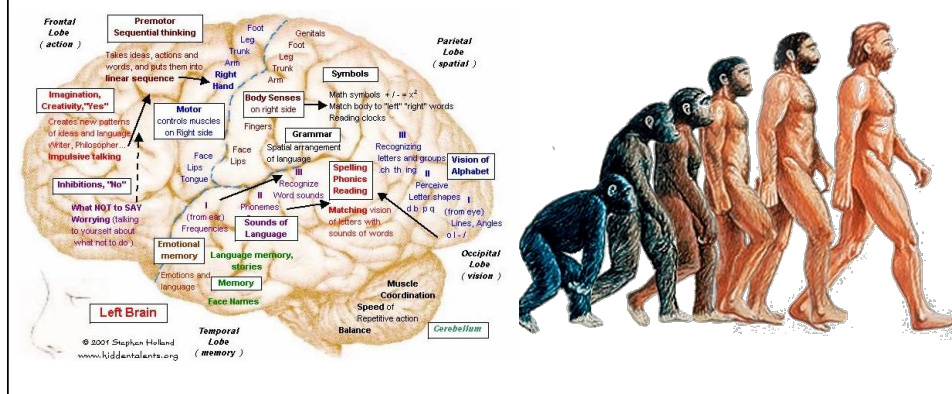
The goal of the new UCLA center, Cong said, is to look beyond parallelization and focus on domain-specific customization to bring significant power-performance efficiency improvement to important application domains.

## Overview of Our Approach -- Customized Computing with Accelerator-Rich Architectures

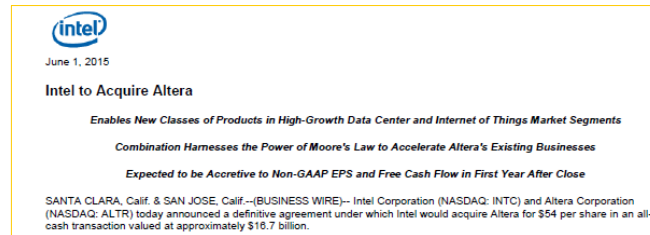
- ◆ Extensive use of dedicated and composable accelerators
  - Most computations are carried on accelerators – not on processors!
- ◆ A fundamental departure from von Neumann architecture
- ◆ Why now?
  - Previous architectures are device/transistor limited
  - Von Neumann architecture allows maximum device reuse
    - One pipeline serves all functions, fully utilized
- ◆ Future architectures
  - Plenty of transistors, but power/energy limited (dark silicon)
  - Customization and specialization for maximum energy efficiency
- ◆ A story of specialization

## Lessons from Nature: Human Brain and Advance of Civilization

- ◆ High power efficiency (20W) of human brain comes from specialization
  - Different region responsible for different functions
- ◆ Remarkable advancement of civilization also from specialization
  - More advanced societies have higher degree of specialization



## Intel's \$16.7B Acquisition of Altera



- Intel CEO Brian Krzanich noted, “The acquisition will couple Intel’s leading-edge products and manufacturing process with Altera’s leading field-programmable gate array (or FPGA) technology.” He further stated, “The combination is expected to enable new classes of products that meet customer needs in the data center and Internet of Things market segments.”

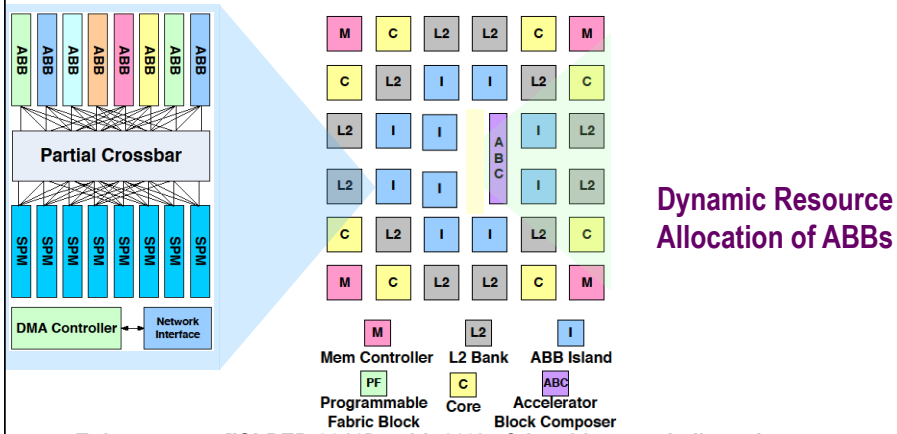
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## Levels of Customization

- ◆ **Single-chip level**
  - Require new processor designs, e.g. using composable accelerators [ISLPED’ 12, DAC’14]
- ◆ **Server node level**
  - Host CPU + FPGA via PCI-e or QPI connections
- ◆ **Data center level**
  - Clusters of heterogeneous computing nodes

## Composable Accelerators with Programmable Fabrics [ISLPED'2013]

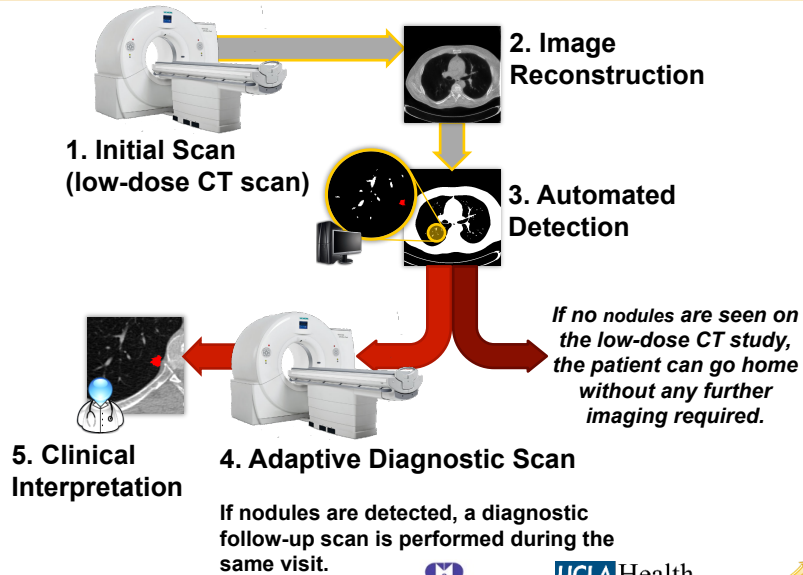


- ◆ **Enhancement [ISLPED 2013]:** with 20% of the chip area dedicated to programmable fabric, we can achieve more:
  - **Flexibility:** An average 8.2x (up to 146x) speedup in other domains, such as commercial, vision and navigation
  - **Longevity:** 22x speedup on a new application within the medical imaging domain

## Levels of Customization

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## A Success Application: Low-Dose Adaptive CT Scan



## 5 Years of Accelerating Medical Image Processing

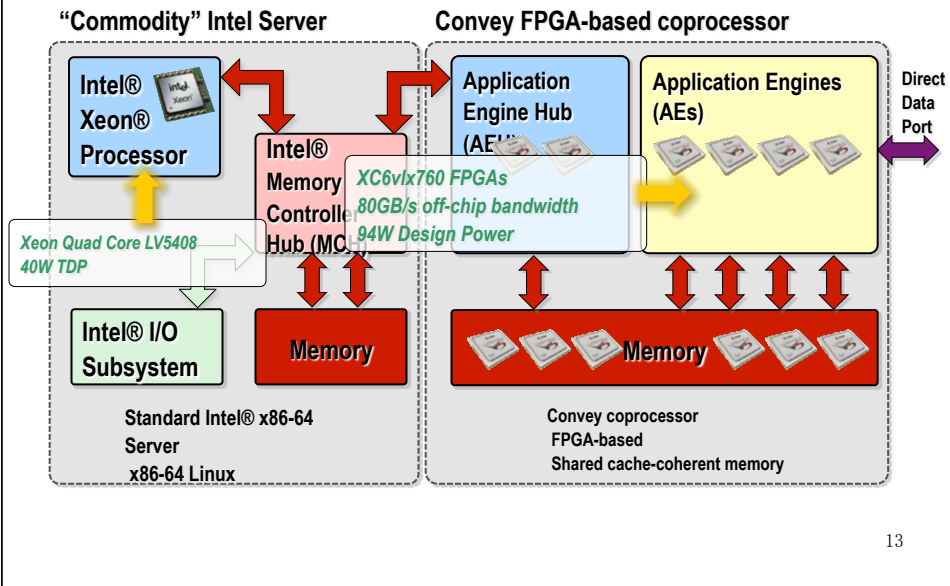
	2010	2013	2015 (Today)
<b>CT image reconstruction</b>	18 hours Single thread CPU	20 minutes FPGA acceleration on Convey	6 minutes 4 Virtex-6 FPGAs on Convey w/data reuse
<b>Denosing</b>	5 minutes Single thread CPU	15 seconds Nvidia GPU	3 seconds Core i7 Haswell, OpenMP, stencils
<b>Registration</b>	10 minutes Single thread CPU	2 minutes Nvidia GPU	30 seconds Core i7 Haswell, OpenMP, stencils
<b>Segmentation</b>	20 minutes Single thread CPU	4 minutes Multithread CPU	1 minute Core i7 Haswell, OpenMP, stencils
<b>Analysis</b>	45 minutes Single thread CPU	18 minutes Multithread CPU	5 minutes* Core i7 Haswell, OpenMP

\* New detection method w/improved accuracy



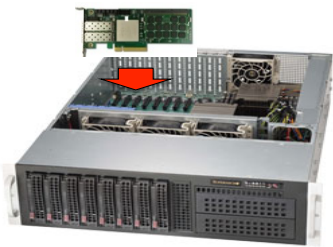
Workstation CPU, GPU, FPGA, CPU

## Example of CDSC Heterogeneous Computing Server

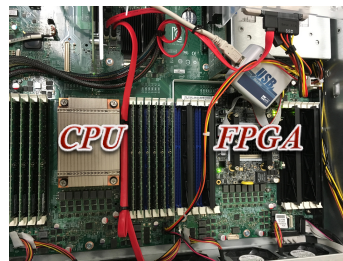


## More CPU-FPGA Platforms

*Alpha Data*  
PCIe-based, Separate Memory



*HARP*  
QPI-based, Shared Memory



## Levels of Customization

### ■ Single-chip level

- Require new processor designs, e.g. using composable accelerators [ISLPED' 12, DAC'14]

### ■ Server node level

- Host CPU + FPGA via PCI-e or QPI connections [DAC'16]

### ■ Data center level

- Clusters of heterogeneous computing nodes [DAC'16]
- How about programming at data center level? [HotCloud'16]

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## Data Center Energy Consumption is a Big Deal

In **2013**, U.S. data centers consumed an estimated **91 billion kilowatt-hours** of electricity, projected to increase to roughly **140 billion kilowatt-hours** annually by **2020**

- **50 large power plants** (500-megawatt coal-fired)
- **\$13 billion annually**
- **100 million metric tons of carbon pollution per year.**

<https://www.nrdc.org/resources/americas-data-centers-consuming-and-wasting-growing-amounts-energy>

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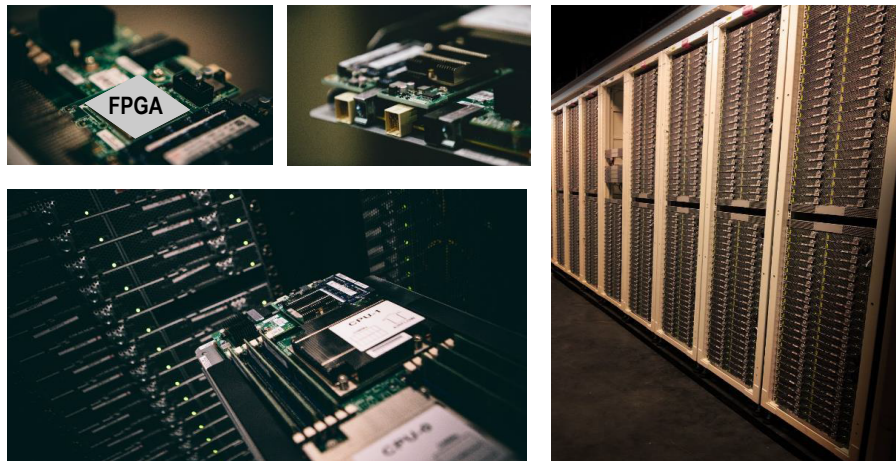


## ***Extensive Efforts on Improving Datacenter Energy Efficiency***

- ◆ **Understand the scale-out workloads**
  - ISCA'10, ASPLOS'12
  - Mismatch between workloads and processor designs;
  - Modern processors are over-provisioning
- ◆ **Trade-off of big-core vs. small-core**
  - ISCA'10: Web-search on small-core with better energy-efficiency
  - Baidu taps Mavell for ARM storage server SoC

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## ***Datacenter Level Integration at Microsoft***



A. Putnam, "A Reconfigurable Fabric for Accelerating Large-Scale Datacenter Services", ISCA'2014

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## ***Focus of Our Study***

- Evaluation of different integration options of heterogeneous technologies in datacenters
- Efficient programming support for heterogeneous datacenters

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## ***Small-core on Compute-intensive Workloads***

- |   |  |
|---|--|
| <ul style="list-style-type: none"> <li>◆ <b>Data set</b> <ul style="list-style-type: none"> <li>■ MNIST 700K Samples</li> <li>■ 784 Features, 10 Labels</li> </ul> </li> <li>◆ <b>Benchmarks (MLLib)</b> <ul style="list-style-type: none"> <li>■ LR: logistic regression</li> <li>■ KM: k-mean clustering</li> </ul> </li> <li>◆ <b>Results</b> <ul style="list-style-type: none"> <li>■ Normalized to reference Xeon performance</li> </ul> </li> </ul> | <ul style="list-style-type: none"> <li>◆ <b>Baselines</b> <ul style="list-style-type: none"> <li>■ Xeon: Intel E5 2620<br/>12 Core CPU 2.40GHz</li> <li>■ Atom: Intel D2500 1.8GHz</li> <li>■ ARM: A9 in Zynq 800MHz</li> </ul> </li> <li>◆ <b>Power consumption (averaged)</b> <ul style="list-style-type: none"> <li>■ Xeon: 175W/node</li> <li>■ Atom: 30W/node</li> <li>■ ARM: 10W/node (embedded )</li> </ul> </li> </ul> |
|---|--|

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## Small Cores Alone Are Not Efficient!

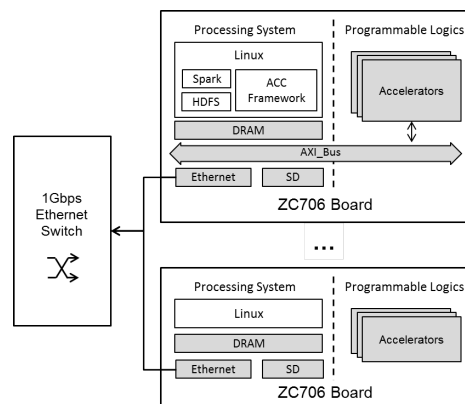
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## Small Core + ACC: FARM

### ◆ Boost Small-core Performance with FPGA



- 8 Xilinx ZC706 boards
- 24-port Ethernet switch
- ~100W power

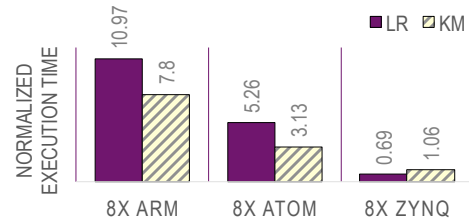


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## Small-core with FPGA Performance

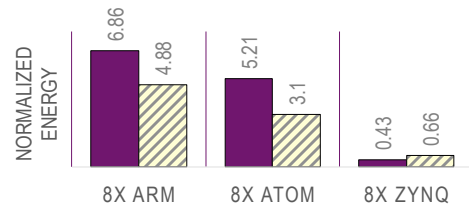
### ◆ Setup

- Data set
  - MNIST 700K Samples
  - 784 Features, 10 Labels
- Power consumption (averaged)
  - Atom: 30W/node
  - ARM: 10W/node



### ◆ Results

- Normalized to reference Xeon performance



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**Small Cores + FPGAs Are More Interesting!**

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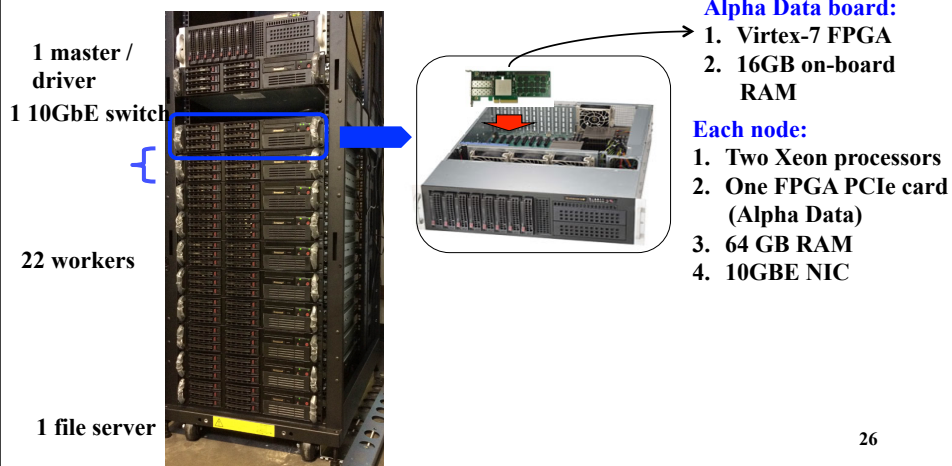
## *Inefficiencies in Small-core*

- ◆ **Slower core and memory clock**
  - Task scheduling is slow
  - JVM-to-FPGA data transfer is slow
- ◆ **Limited DRAM size and Ethernet bandwidth**
  - Slow data shuffling between nodes
- ◆ **Another option: Big-core + FPGA**

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## *Big-Core + ACC: CDSC FPGA-Enabled Cluster*

- ◆ **A 24-node cluster with FPGA-based accelerators**
  - Run on top of Spark and Hadoop (HDFS)



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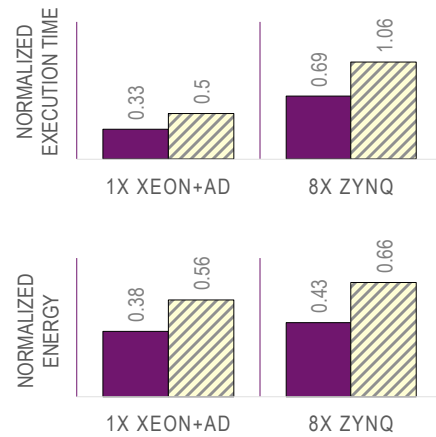
## Experimental Results

### ◆ Experimental setup

- Data set
  - MNIST 700K Samples
  - 784 Features, 10 Labels

### ◆ Results

- Normalized to reference Xeon performance



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## Overall Evaluation Results

### ◆ Based on two machine learning workloads

- Normalized performance (speedup), and energy efficiency (performance/W) relative to big-core solutions

	Performance	Energy-Efficiency
Big-Core+FPGA	Best   2.5	Best   2.6
Small-Core+FPGA	Better   1.2	Best   1.9
<i>Big-Core</i>	<i>Good</i>   1.0	<i>Good</i>   1.0
Small-Core	Bad   0.25	Bad   0.24

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## How to Program Such “Beasts”?

-- “Write Once, Accelerate Anywhere”

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### C/C++ Based Synthesis for Accelerator Design

*xPilot (UCLA 2016) -> AutoPilot (AutoESL) -> Vivado HLS (Xilinx 2011-)*

```

    graph TD
      subgraph Design_Specification [Design Specification]
        A[C/C++/SystemC]
        B[User Constraints]
      end
      subgraph AutoPilot_Temp [AutoPilot™]
        C[Compilation & Elaboration]
        D[Code transformation & opt]
        E[Behavioral & Communication Synthesis and Optimizations]
      end
      subgraph Platform_Characterization [Platform Characterization Library]
        F[(Platform Characterization Library)]
      end
      subgraph RTL_Stage [RTL HDLs & RTL SystemC]
        G[RTL HDLs & RTL SystemC]
      end
      subgraph Timing_Constraints [Timing/Power/Layout Constraints]
        H[Timing/Power/Layout Constraints]
      end
      subgraph Output [FPGA or ASIC blocks]
        I[FPGA or ASIC blocks]
      end
      subgraph Simulation [Simulation, Verification, and Prototyping]
        J[Simulation, Verification, and Prototyping]
      end

      A --> C
      B --> C
      C --> D
      D --> E
      F --> E
      E --> G
      E --> H
      G --> I
      H --> I
      J --> A
  
```

- ◆ Platform-based C to RTL synthesis
- ◆ Synthesize pure ANSI-C and C++, GCC-compatible compilation flow
- ◆ Full support of IEEE-754 floating point data types & operations
- ◆ Efficiently handle bit-accurate fixed-point arithmetic
- ◆ SDC-based scheduling
- ◆ Automatic memory partitioning
- ◆ ...

QoR matches or exceeds manual RTL for many designs

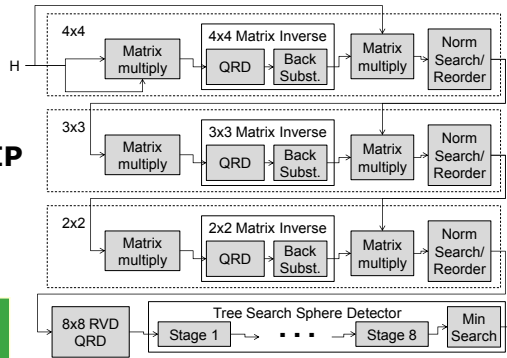
Developed by AutoESL, acquired by Xilinx in Jan. 2011

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## AutoPilot Results: Sphere Decoder (from Xilinx)

- **Wireless MIMO Sphere Decoder**
  - ~4000 lines of C code
  - Xilinx Virtex-5 at 225MHz
- **Compared to optimized IP**
  - 11-31% better resource usage

Metric	RTL Expert	AutoPilot Expert	Diff (%)
LUTs	32,708	29,060	-11%
Registers	44,885	31,000	-31%
DSP48s	225	201	-11%
BRAMs	128	99	-26%



TCAD April 2011 (keynote paper)  
 "High-Level Synthesis for FPGAs: From Prototyping to Deployment"

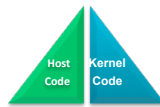
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## SDAccel Development Environment

SDAccel supports OpenCL 1.0 Embedded Profile with some 1.2 / 2.0 features

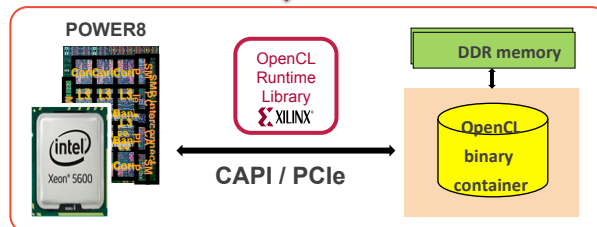
### Host code

- OpenCL APIs
- C / C++



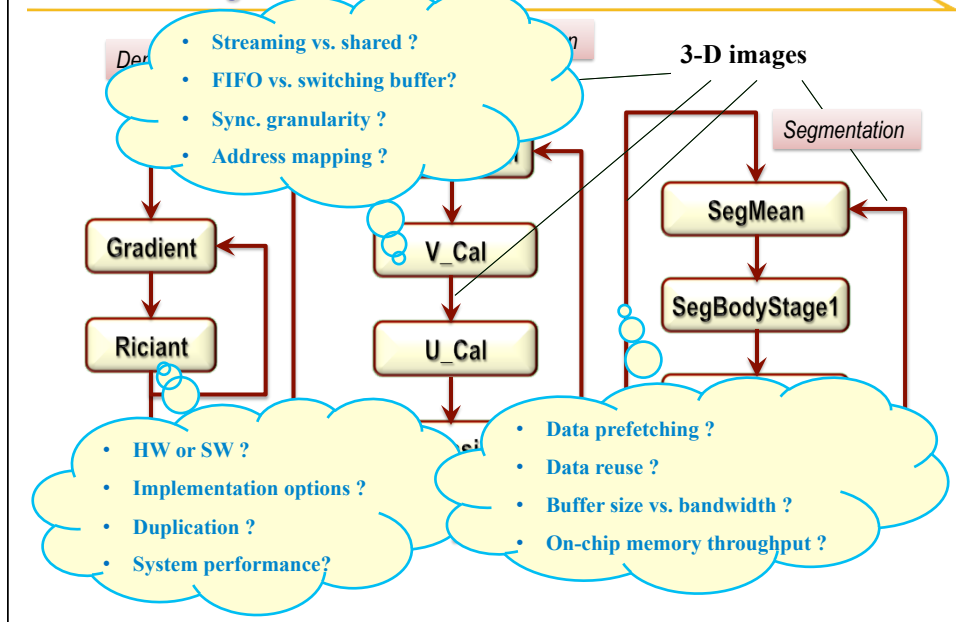
### Kernel code

- OpenCL kernel code
- C/C++
- RTL IP
- 3<sup>rd</sup> party library code

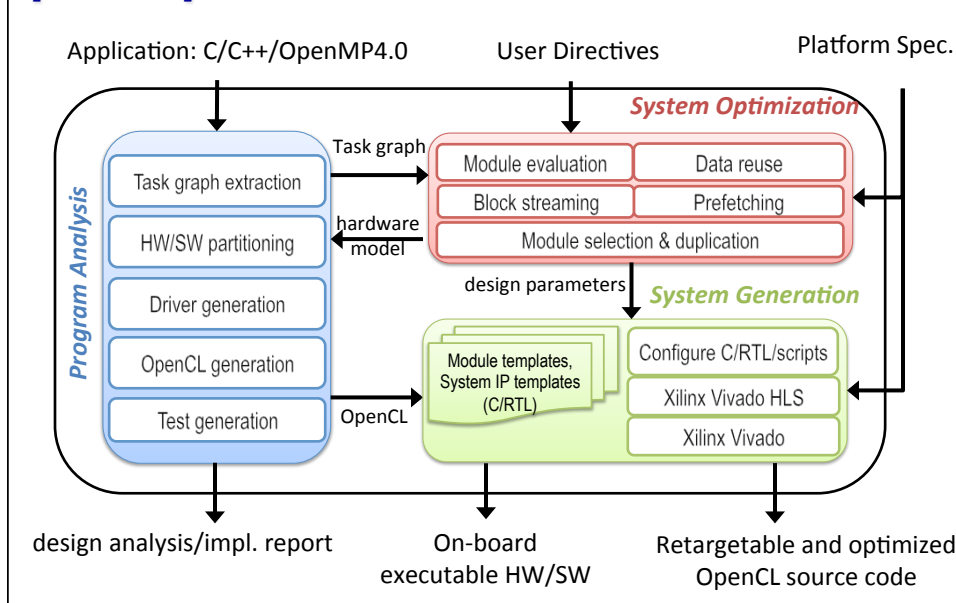




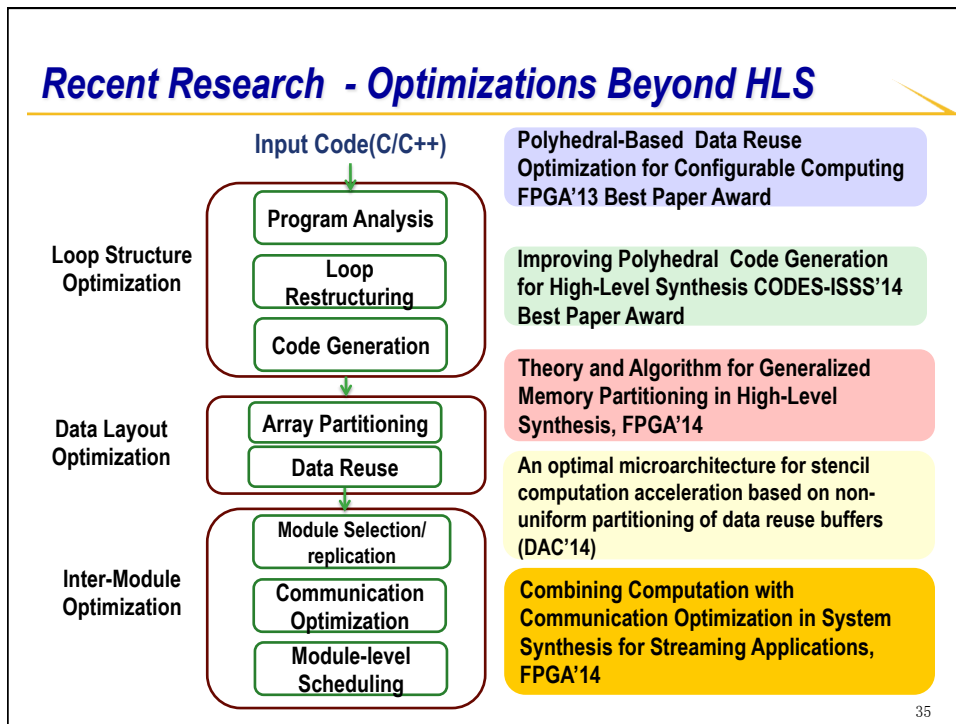
## Design Complexity Can Still be High – Example: Medical Image Processing Pipeline



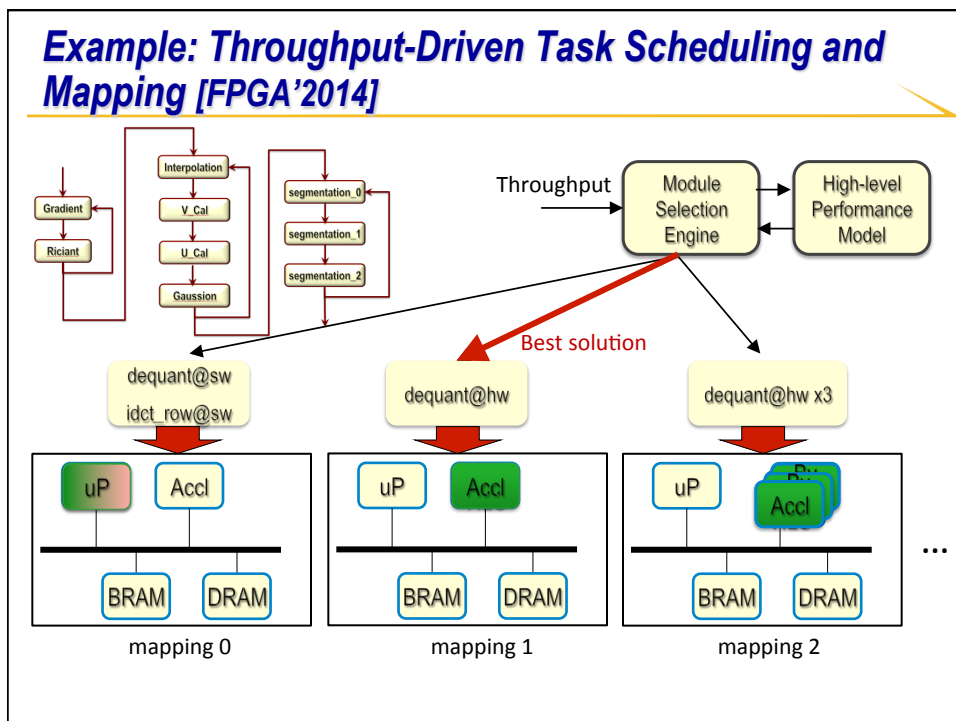
## CMOST: Fully Automated Compilation and Mapping Flow [DAC 2015]



## Recent Research - Optimizations Beyond HLS

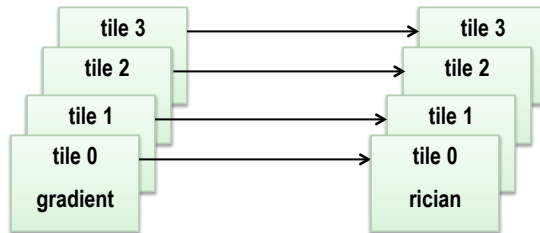


## Example: Throughput-Driven Task Scheduling and Mapping [FPGA'2014]



## Motivation

Tile size: 32x32  
Image: 64x64, 4 tiles



■ Which implementation to use for each module?

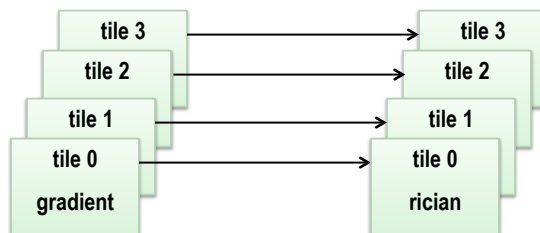
■ Memory partitioned v.s. non-memory-partitioned

	BRAM	DSP	FF	LUT
non-partitioned gradient	128	21	2511	2125
partitioned gradient	176	56	7147	7262
partitioned rician	128	22	4692	3991
non-partitioned rician	176	88	14475	15537

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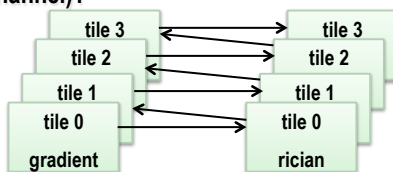
## Motivation

Tile size: 32x32  
Image: 64x64, 4 tiles

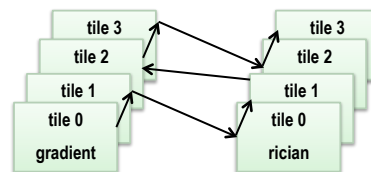


■ How many number of replicas?

■ Scheduling and Communication cost (number of tiles in the communication channel)?



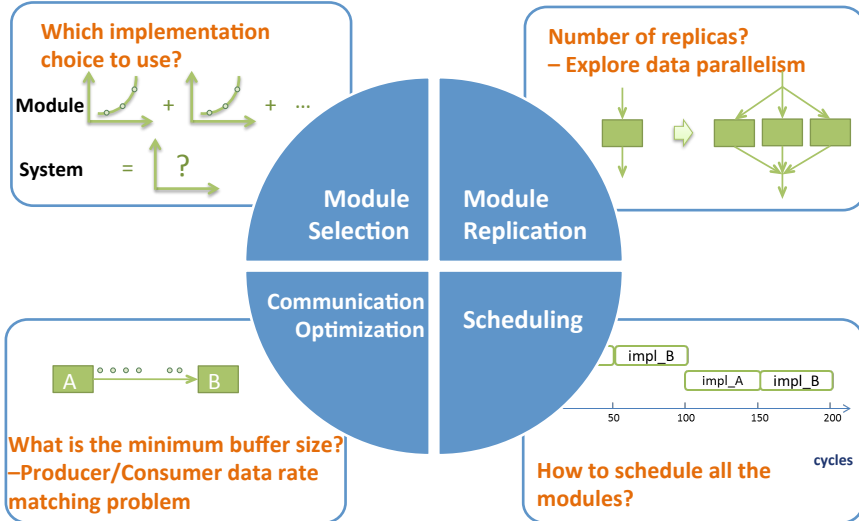
scheduling 0 → 1 tile



scheduling 0 → 2 tiles

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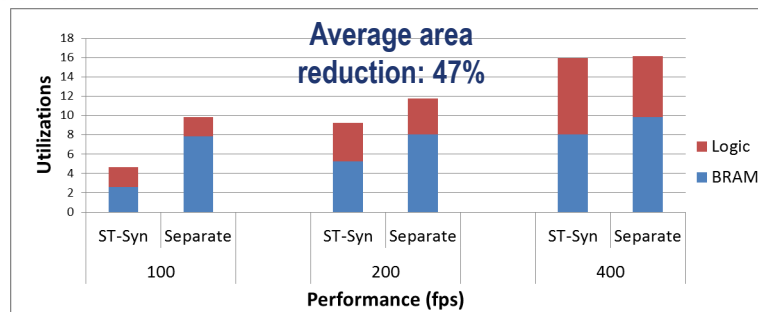
## A Rich Design Space: System-Level Synthesis with HLS for Streaming Applications



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## Experiments on Example Denoise

- **Our methodology: ST-Syn**
  - computation & communication co-optimization
- **Separate:**
  - separate computation opt. + communication opt.
- **→ Communication and computation should be considered in a unified framework**



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## More is Needed for Data Center Level Deployment

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## Scalable Big-Data Programming

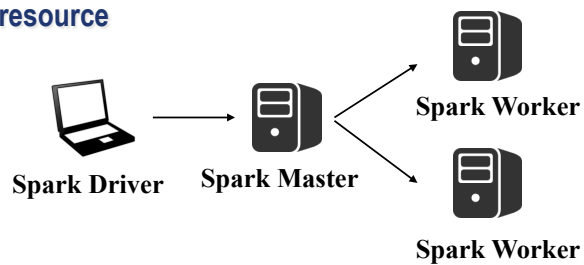
- **Simplified programming models**

- MapReduce, Dataflow

- **User-transparent Runtime**

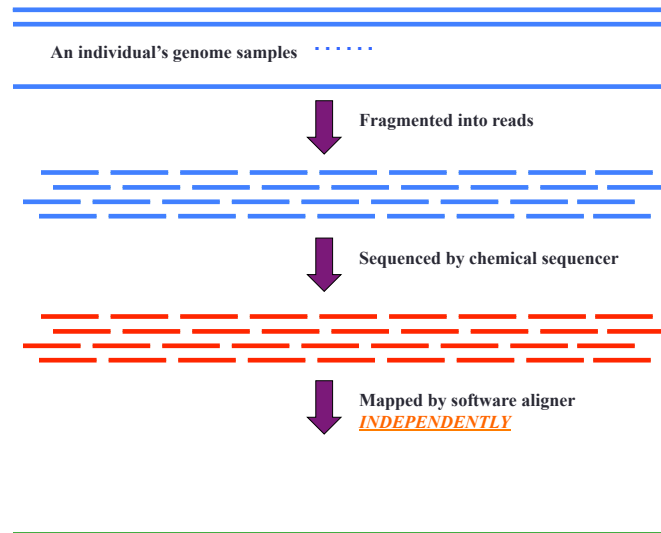
- Distributed computing
- Scheduling and resource management
- Fault-tolerance

```
val points = sc.textfile().cache()
for (i <- 1 to ITERATIONS) {
  val gradient = points.map(p =>
    (1 / (1 + exp(-p.y*(w dot p.x)))
    - 1) * p.y * p.x
  ).reduce(_ + _)
  w -= gradient
}
```



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## Next-Generation DNA Sequencing



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## The Solution: Heterogeneous Cluster Computing

- Processing billions of reads (strings) independently
  - Fit the MapReduce programming model perfectly
  - As for the long reference genome? Spark's broadcast variables
- Inside each read's alignment process
  - Step #1: Seeding
    - Exact string matching
    - Linear time complexity
  - Step #2: Extending
    - Approximate string matching
    - The Smith-Waterman dynamic programming algorithm (Quadratic time complexity)
    - Accelerated by FPGAs

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## Straightforward Integration: $1+1 < 0.001$

### The Spark Program

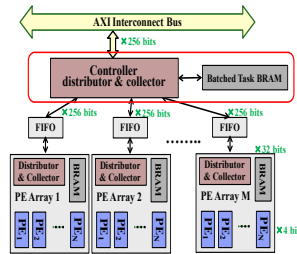
- CS-BWAMEM [HitSeq '15]
- Aligning billions of short reads onto the reference human genome in parallel

### The Accelerator [FCCM '15]

- A throughput-oriented FPGA accelerator for the Smith-Waterman DP kernel

### The Straightforward JNI Integration

- CPU:  $2.1 \times 10^3$  reads per second
- FPGA: 1.6 reads per second

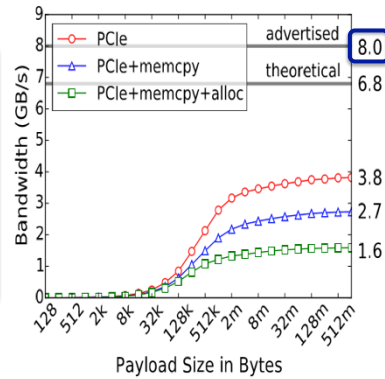
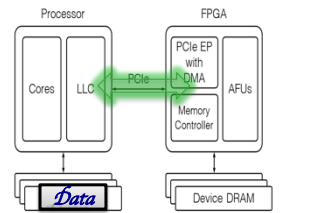
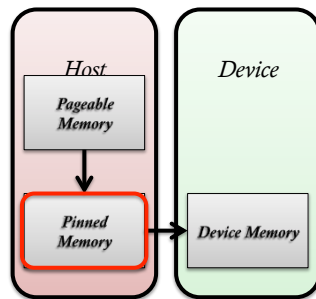


On CPU	On FPGA
One read	One DP
⇒ 24 DPs	⇒ 25 ms data transfer
⇒ 20 μs per DP	⇒ 1.6 reads/s
⇒ $2.1 \times 10^3$ reads/s	

While JNI serves as a standard approach to connect JVMs with FPGAs, a straightforward integration through JNI degrades the performance by **1000x**.

## What happened in a CPU-FPGA communication instance?

- Java Heap ↔ Native Memory
- Host Memory ↔ Device Memory



### Why communication matters?

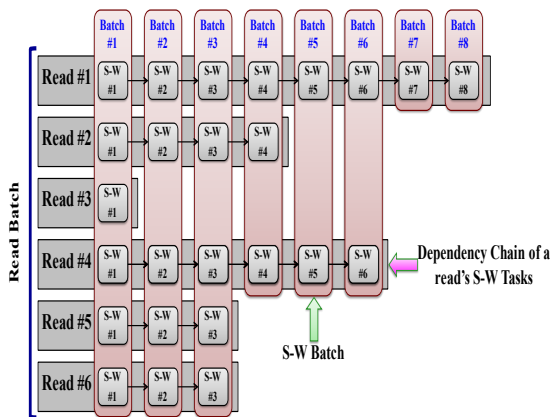
- Each map function is likely to process only a small volume of data with a small amount of execution time
  - One read is only 101 ASCII characters
  - One line of a text file
  - One record of a NoSQL table
  - ...
- Communication overhead can be amortized by batch processing

```
def map_func(input:U):V = {
  // U => P => Q => V
  t1:P = cnv1(input)
  t2:Q = cnv2(t1)
  t3:V = cnv3(t2)
  t3
}
rdd_out = rdd_in.map(ele=>map_func(ele))
```

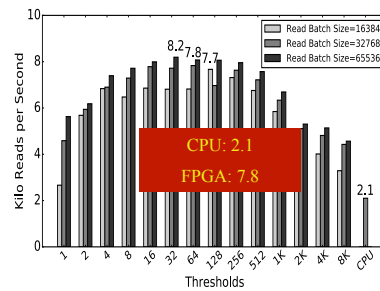
```
def map_func(input:Array[U]):Array[V] = {
  // Array[U] => ... => Array[V]
  t1:Array[P] = cnv1_batch(input)
  t2:Array[Q] = cnv2_batch(t1)
  t3:Array[V] = cnv3_batch(t2)
  t3
}
rdd_out = rdd_in.map(ele=>map_func(ele))
```

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### Let's first do batch processing manually



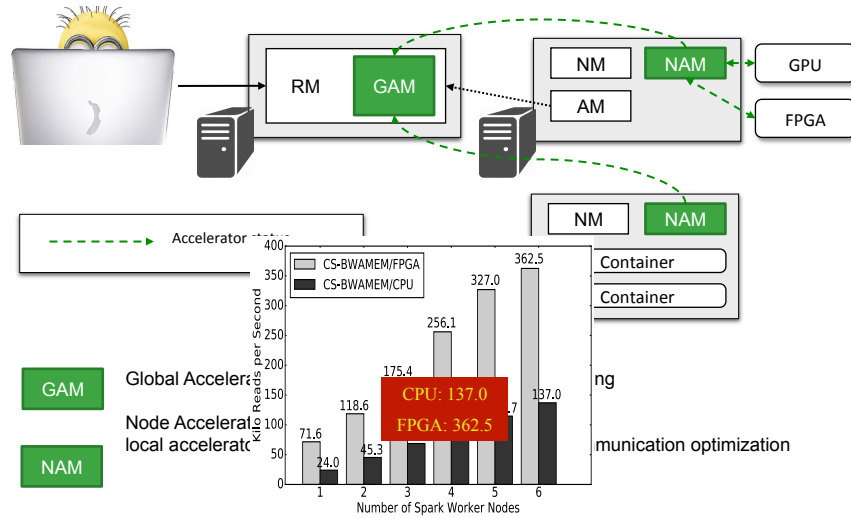
Dependency/Irregularity-Aware Batch Processing



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## Accelerator-as-a-Service



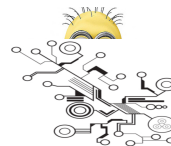
Source: <https://spark-summit.org/2016/events/deploying-accelerators-at-datacenter-scale-using-spark/>

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## Blaze Runtime System

### ➤ A system providing Accelerator-as-a-Service

- Provide a better programming model:
  - APIs for accelerator developers
    - Easier to integrate into big-data workload, e.g. Spark and Hadoop
  - APIs for big-data application developers
    - Requires no knowledge about accelerators
- Provide an accelerator management runtime
  - Supports FPGAs and GPUs

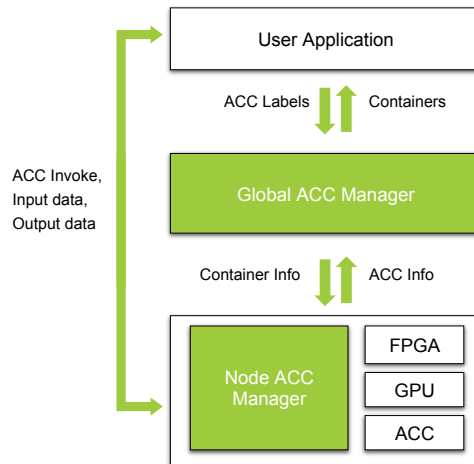


Source: <https://spark-summit.org/2016/events/deploying-accelerators-at-datacenter-scale-using-spark/>

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## Runtime Flow

- **Accelerator Registration**
  - Register accelerator service to corresponding nodes
- **Job Accelerator Request**
  - Use `acc_id` as label
  - GAM allocates containers to corresponding nodes
- **Job execution**
  - Adopts several optimization techniques, e.g. Double-buffering, caching

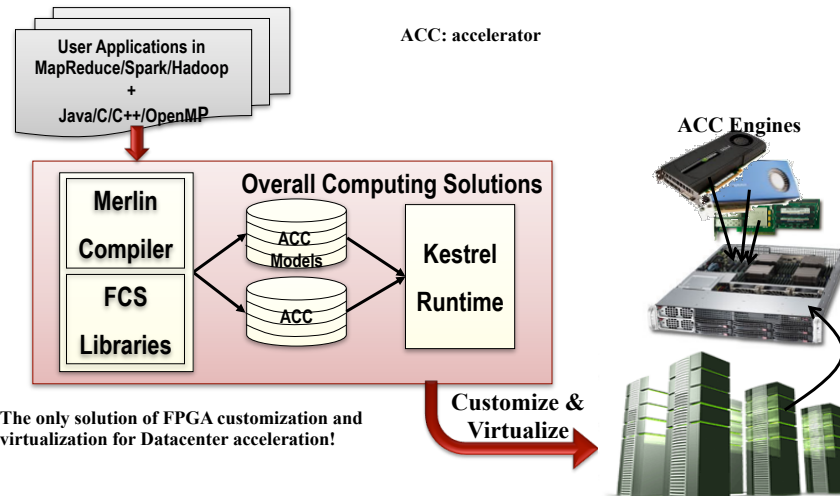


Source: <https://spark-summit.org/2016/events/deploying-accelerators-at-datacenter-scale-using-spark/>

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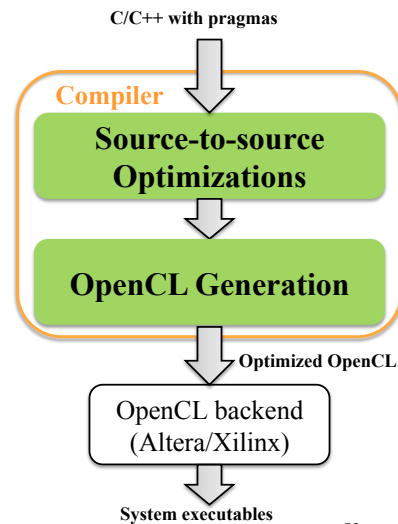


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## Merlin Compiler

- ◆ C-based design flow
- ◆ OpenMP-like high-level programming model
- ◆ Automatic optimizations for productivity and QoR
- ◆ Same input for multi-vendors and multi-platforms



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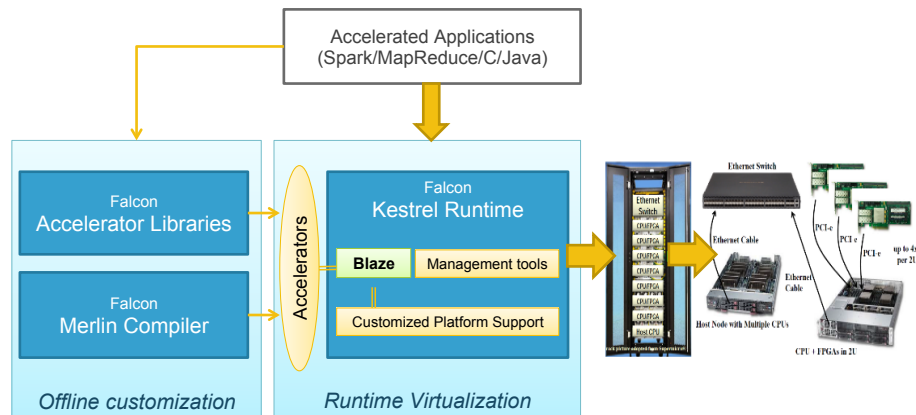
## Sample Compilation Results

Design	Merlin Compiler	Initial OpenCL	Manual Optimized OpenCL
Blackschole	0.34ms	11ms	NA
Denoise	0.08s	3.8s	NA
LogisticRegr	94ms	3.7s	94ms
MatMult	0.8ms	1.9ms	0.8ms
NAMD	26ms	51ms	26ms
Normal	4ms	52ms	10ms
TwoNN	1.23s	1.70s	NA
<b>Average</b>	<b>1x</b>	<b>21x</b>	<b>1.3x</b>

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## Kestrel Runtime And Blaze



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## Concluding Remarks

- ◆ **New era of computing**
  - Accelerator-centric computing
  - Need efficient support for customization and specialization
- ◆ **Customization at all levels**
  - Chip-level
  - Server node level
  - Data center level
- ◆ **Data center level customization holds great promise**
  - That's where workload aggregates
- ◆ **Software is the key**
  - Programming models
    - Hadoop/MapReduce or SPARK (+ C/C++), OpenMP, OpenCL,, ...
  - Compilation support
  - Runtime management

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Sarkar  
(Associate Dir)  
(Rice)



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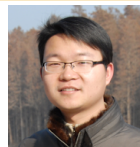
## Postdocs, Graduate Students, and Collaborators



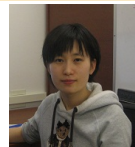
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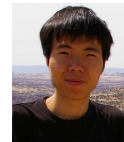
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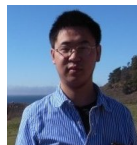
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